

Models for warping functions and registration

Karthik Bharath

University of Nottingham

- ▶ Work with Sebastian Kurtek (with much help from Anuj, Eric and Huiling Le)
- ▶ Supported by NSF (DMS 1613054); NIH (R01-CA214955).

NSF-CBMS workshop on Elastic Functional Data Analysis 2018

This talk...

- ▶ Statistical models on function spaces for elastic functional data and issues.
- ▶ Model-based pairwise registration of curves/functions.
- ▶ How to define and sample from distribution on warping functions of $[0, 1]$ and \mathbb{S}^1 ?
- ▶ One or two applications.

Where to define models for elastic functional data?

- ▶ **Original data space**

Functions: $\mathbb{L}^2([0, 1], \mathbb{R})$;

Curves: $AC(D, \mathbb{R}^n)$, $\mathbb{L}^2(D, \mathbb{R}^n)$ where $D \in \{[0, 1], \mathbb{S}^1\}$.

Where to define models for elastic functional data?

- ▶ **Original data space**

Functions: $\mathbb{L}^2([0, 1], \mathbb{R})$;

Curves: $AC(D, \mathbb{R}^n)$, $\mathbb{L}^2(D, \mathbb{R}^n)$ where $D \in \{[0, 1], \mathbb{S}^1\}$.

- ▶ **Ambient/Top/Pre-shape space**

Functions: $\mathbb{L}^2([0, 1], \mathbb{R})$ (or sometimes \mathbb{S}^∞);

Curves: \mathbb{S}^∞ (open) or its subset (closed).

Where to define models for elastic functional data?

- ▶ **Original data space**

Functions: $\mathbb{L}^2([0, 1], \mathbb{R})$;

Curves: $AC(D, \mathbb{R}^n)$, $\mathbb{L}^2(D, \mathbb{R}^n)$ where $D \in \{[0, 1], \mathbb{S}^1\}$.

- ▶ **Ambient/Top/Pre-shape space**

Functions: $\mathbb{L}^2([0, 1], \mathbb{R})$ (or sometimes \mathbb{S}^∞);

Curves: \mathbb{S}^∞ (open) or its subset (closed).

- ▶ **Quotient/Shape space**

Functions: $\mathbb{L}^2([0, 1], \mathbb{R})/\Gamma$ where Γ is group of warp maps of $[0, 1]$;

Curves: $\mathbb{S}^\infty/(\Gamma \times SO(n))$ for open curves.

Where to define models for elastic functional data?

Laws of stochastic processes are natural models:

Where to define models for elastic functional data?

Laws of stochastic processes are natural models:

- ▶ **Original data space.** Easy.

For e.g. Gaussian process on $\mathbb{L}^2(D, \mathbb{R}^n)$; diffusion bridges as solutions of SDEs.

Where to define models for elastic functional data?

Laws of stochastic processes are natural models:

- ▶ **Original data space.** **Easy.**

For e.g. Gaussian process on $\mathbb{L}^2(D, \mathbb{R}^n)$; diffusion bridges as solutions of SDEs.

- ▶ **Ambient/Top/Pre-shape space.** **Hard.**

For e.g. Marginalization/projection of Gaussian measure on \mathbb{L}^2 to get one on \mathbb{S}^∞ is not straightforward.

Where to define models for elastic functional data?

Laws of stochastic processes are natural models:

- ▶ **Original data space.** *Easy.*

For e.g. Gaussian process on $\mathbb{L}^2(D, \mathbb{R}^n)$; diffusion bridges as solutions of SDEs.

- ▶ **Ambient/Top/Pre-shape space.** *Hard.*

For e.g. Marginalization/projection of Gaussian measure on \mathbb{L}^2 to get one on \mathbb{S}^∞ is not straightforward.

- ▶ **Quotient/Shape space.** *Impossibly hard.*

No invariant measure for infinite-dimensional warping group.

Where to define models for elastic functional data?

Laws of stochastic processes are natural models:

- ▶ **Original data space.** Easy.

For e.g. Gaussian process on $\mathbb{L}^2(D, \mathbb{R}^n)$; diffusion bridges as solutions of SDEs.

- ▶ **Ambient/Top/Pre-shape space.** Hard.

For e.g. Marginalization/projection of Gaussian measure on \mathbb{L}^2 to get one on \mathbb{S}^∞ is not straightforward.

- ▶ **Quotient/Shape space.** Impossibly hard.

No invariant measure for infinite-dimensional warping group.

In principle, we can have $p(\text{data}) = \int p(\text{data}|\text{group})dp(\text{group})$.

Example: mean estimation with marginal models

Models for a random curve that are roughly of the form

$$X(t) = (\mu(t), g(t)) \quad \text{"+"} \quad \epsilon(t), \quad g \in G$$

where:

- ▶ ϵ is a stochastic process (likelihood given g);
- ▶ (μ, g) is action of group element g on μ ;
- ▶ μ is a deterministic mean/template;
- ▶ g is a stochastic process (random effect/prior on G)

Integrate out g over G .

Focus of this talk: Stochastic pairwise registration

Let $\Gamma := \{\gamma : D \rightarrow D\}$ be a class of warping functions.

Match $f_i : D \rightarrow \mathbb{R}^k, i = 1, 2$ with:

Focus of this talk: Stochastic pairwise registration

Let $\Gamma := \{\gamma : D \rightarrow D\}$ be a class of warping functions.

Match $f_i : D \rightarrow \mathbb{R}^k, i = 1, 2$ with:



$$\arg \min_{\gamma \in \Gamma} d(f_1, (f_2, \gamma)),$$

with a **distribution on Γ** ;

Focus of this talk: Stochastic pairwise registration

Let $\Gamma := \{\gamma : D \rightarrow D\}$ be a class of warping functions.

Match $f_i : D \rightarrow \mathbb{R}^k, i = 1, 2$ with:



$$\arg \min_{\gamma \in \Gamma} d(f_1, (f_2, \gamma)),$$

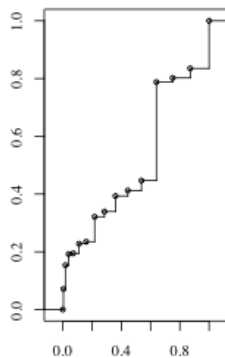
with a **distribution on Γ** ;

- ▶ or a posterior summary based on a Bayesian model:

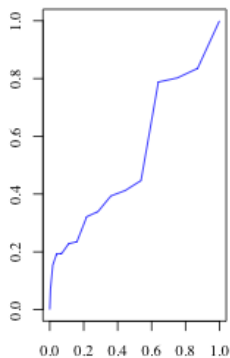
likelihood on $\{f_1(t) - (f_2, \gamma) | \gamma\}$ **and prior distribution on Γ** .

Candidate classes of warping functions

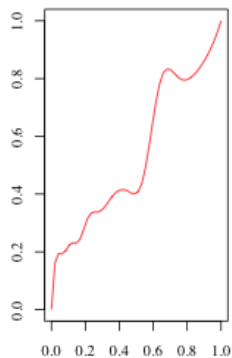
Step function



Piecewise Linear



Diffeomorphism



Distributions on warping functions on $[0, 1]$

We wish to have a random function $\gamma : [0, 1] \rightarrow [0, 1]$, increasing with $\gamma(0) = 0$ and $\gamma(1) = 1$.

¹E. Shavgulidze. *Trudy Math. Inst. Steklov.*, 217 (1997),189-208

²E. Bardelli and A. G. Menucci. *Journal of Geometric Mechanics*. 9 (2017), 291-316.

Distributions on warping functions on $[0, 1]$

We wish to have a random function $\gamma : [0, 1] \rightarrow [0, 1]$, increasing with $\gamma(0) = 0$ and $\gamma(1) = 1$.

- ▶ No 'Haar' measure on Γ —only those quasi-invariant with respect to composition exist. ¹.

¹E. Shavgulidze. *Trudy Math. Inst. Steklov.*, 217 (1997),189-208

²E. Bardelli and A. G. Menucci. *Journal of Geometric Mechanics*. 9 (2017), 291-316.

Distributions on warping functions on $[0, 1]$

We wish to have a random function $\gamma : [0, 1] \rightarrow [0, 1]$, increasing with $\gamma(0) = 0$ and $\gamma(1) = 1$.

- ▶ No 'Haar' measure on Γ —only those quasi-invariant with respect to composition exist. ¹.
- ▶ Pushforwards of equivalent Gaussian measures on \mathbb{L}^2 tangent spaces of \mathbb{S}^∞ under Exponential maps under are mutually singular. ².

¹E. Shavgulidze. *Trudy Math. Inst. Steklov.*, 217 (1997),189-208

²E. Bardelli and A. G. Menucci. *Journal of Geometric Mechanics*. 9 (2017), 291-316.

Distributions on warping functions on $[0, 1]$

We wish to have a random function $\gamma : [0, 1] \rightarrow [0, 1]$, increasing with $\gamma(0) = 0$ and $\gamma(1) = 1$.

- ▶ No 'Haar' measure on Γ —only those quasi-invariant with respect to composition exist. ¹.
- ▶ Pushforwards of equivalent Gaussian measures on \mathbb{L}^2 tangent spaces of \mathbb{S}^∞ under Exponential maps under are mutually singular. ².
- ▶ Subordinator processes (a.s. non-negative, non-decreasing Levy process) are natural candidates (e.g. Gamma process).

¹ E. Shavgulidze. *Trudy Math. Inst. Steklov.*, 217 (1997), 189-208

² E. Bardelli and A. G. Menucci. *Journal of Geometric Mechanics*. 9 (2017), 291-316.

Distributions on warping functions on $[0, 1]$

We wish to have a random function $\gamma : [0, 1] \rightarrow [0, 1]$, increasing with $\gamma(0) = 0$ and $\gamma(1) = 1$.

- ▶ No 'Haar' measure on Γ —only those quasi-invariant with respect to composition exist. ¹.
- ▶ Pushforwards of equivalent Gaussian measures on \mathbb{L}^2 tangent spaces of \mathbb{S}^∞ under Exponential maps under are mutually singular. ².
- ▶ Subordinator processes (a.s. non-negative, non-decreasing Levy process) are natural candidates (e.g. Gamma process).
- ▶ Define a map $\Phi : C_0[0, 1] \rightarrow \text{Diff}^1[0, 1]$ as

$$g(t) \mapsto \Phi(g(t)) := \frac{\int_0^t e^{g(s)} ds}{\int_0^1 e^{g(s)} ds}.$$

Choose g to be a Gaussian process for e.g.

¹E. Shavgulidze. *Trudy Math. Inst. Steklov.*, 217 (1997),189-208

²E. Bardelli and A. G. Menucci. *Journal of Geometric Mechanics*. 9 (2017), 291-316.

Distributions on warping functions on $[0, 1]$

We wish to have a random function $\gamma : [0, 1] \rightarrow [0, 1]$, increasing with $\gamma(0) = 0$ and $\gamma(1) = 1$.

- ▶ No 'Haar' measure on Γ —only those quasi-invariant with respect to composition exist. ¹.
- ▶ Pushforwards of equivalent Gaussian measures on \mathbb{L}^2 tangent spaces of \mathbb{S}^∞ under Exponential maps under are mutually singular. ².
- ▶ Subordinator processes (a.s. non-negative, non-decreasing Levy process) are natural candidates (e.g. Gamma process).
- ▶ Define a map $\Phi : C_0[0, 1] \rightarrow \text{Diff}^1[0, 1]$ as

$$g(t) \mapsto \Phi(g(t)) := \frac{\int_0^t e^{g(s)} ds}{\int_0^1 e^{g(s)} ds}.$$

Choose g to be a Gaussian process for e.g.

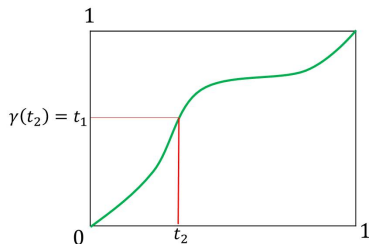
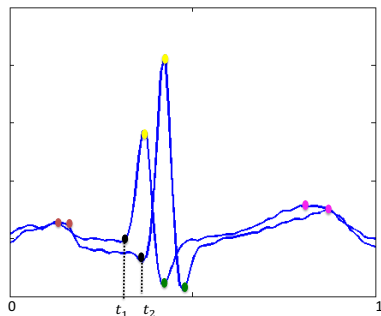
Statistical issue: Not easy to centre these distributions at desired γ or sample from.

¹E. Shavgulidze. *Trudy Math. Inst. Steklov.*, 217 (1997),189-208

²E. Bardelli and A. G. Menucci. *Journal of Geometric Mechanics*. 9 (2017), 291-316.

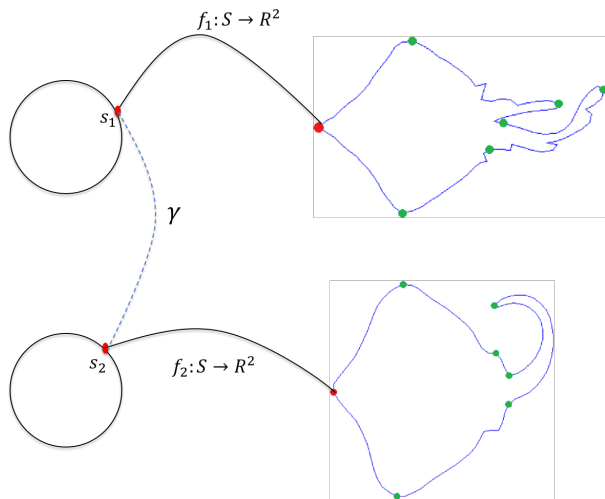
A new variant of the curve/function registration problem is common and motivates the class of warping functions.

Pairwise alignment with landmarks



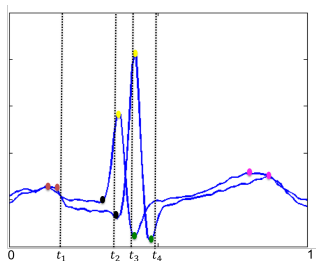
- ▶ If on f_1 a landmark is present at $t_1 \in [0, 1]$ and correspondingly at t_2 on f_2 , then there is a warping constraint: $\gamma(t_2) = t_1$.

Pairwise alignment with landmarks



Desiderata in a \mathbb{P}_θ on Γ

Desiderata in a \mathbb{P}_θ on Γ

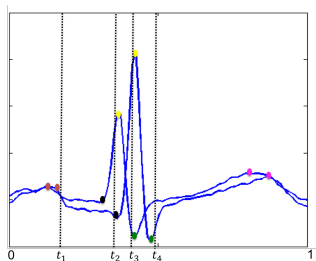


Decompose **global** alignment
into multiple **local** ones:

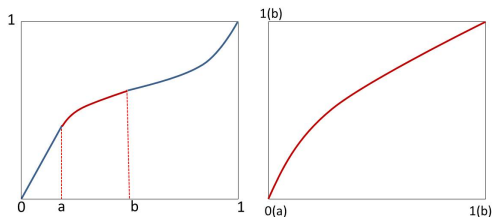
\mathbb{P}_θ restricted to $\gamma|_{[t_1, t_2]}$ is **in-**
dependent of \mathbb{P}_θ restricted to

$\gamma|_{[0,1] \setminus [t_1, t_2]}$ (**Markov like**)

Desiderata in a \mathbb{P}_θ on Γ



Decompose **global** alignment into multiple **local** ones:
 \mathbb{P}_θ restricted to $\gamma|_{[t_1, t_2]}$ is **independent** of \mathbb{P}_θ restricted to $\gamma|_{[0,1] \setminus [t_1, t_2]}$ (**Markov like**)



Optimal local alignment 'matches'
optimal global one ^a:

$$\mathbb{P}_{\theta(t_2-t_1)} \text{ (Self-similarity)}$$

^a *Focus Invariance*: A. Trounev and L. Younes. *SIAM Journal on Control and Optimization*, 39:1112-1135, 2000

Program

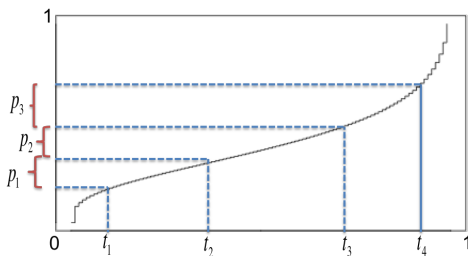
- ▶ Landmark constraints imply that diffeomorphism group for Γ is not appropriate.
- ▶ Decomposability and Markov-like property point towards a process with independent increments. (Levy)

Program

- ▶ Landmark constraints imply that diffeomorphism group for Γ is not appropriate.
- ▶ Decomposability and Markov-like property point towards a process with independent increments. (Levy)
- ▶ We first examine a simple sampling algorithm, and then pose the question:

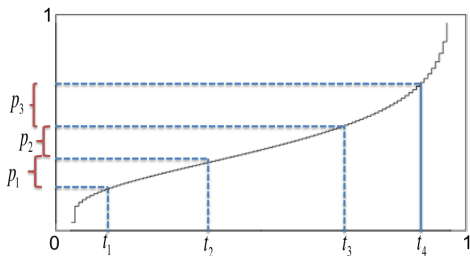
"Does there exist a distribution \mathbb{P}_θ from which the warping functions are being sampled from? Does it possess the desiderata?"

(Remarkably simple) Sampling algorithm ³



1. Choose a (non-random) set of ordered points
 $0 =: t_0 < t_1 < t_2 < \dots < t_{n-1} < t_n := 1$;
2. sample (p_1, \dots, p_n) from **Dirichlet distribution** with parameters $\theta(1, \dots, 1)$;
3. construct a warp map on $[0, 1]$ by linear interpolation.

Sampling algorithm: A generalisation



1. Choose a (non-random) set of ordered points
 $0 =: t_0 < t_1 < t_2 < \dots < t_{n-1} < t_n := 1$;
2. set $p_i = x_{i:n} - x_{i-1:n}$, $i = 1, \dots, n$, where $x_{i:n}$ are order statistics from F . ($x_i \sim U[0, 1]$ implies $(p_1, \dots, p_n) \sim \text{Dirichlet}(1, \dots, 1)$);
3. construct a warp map on $[0, 1]$ by linear interpolation.

'Nice' distribution as $n \rightarrow \infty$?

Consider the process

$$Y_n(t) := \sum_{i=1}^{\lfloor nt \rfloor} p_i + (nt - \lfloor nt \rfloor)p_{\lfloor nt \rfloor + 1}, \quad t \in [0, 1].$$

'Nice' distribution as $n \rightarrow \infty$?

Consider the process

$$Y_n(t) := \sum_{i=1}^{\lfloor nt \rfloor} p_i + (nt - \lfloor nt \rfloor)p_{\lfloor nt \rfloor + 1}, \quad t \in [0, 1].$$

Proposition (Degenerate distribution)

1. **Algorithm of Chen et al.**

Under a uniform partition, in $C([0, 1])$ with uniform topology: Y_n converges in probability to $\gamma(t) = t$; the process $\sqrt{n}(Y_n(t) - t)$ converges in distribution to a standard Brownian Bridge process.

'Nice' distribution as $n \rightarrow \infty$?

Consider the process

$$Y_n(t) := \sum_{i=1}^{\lfloor nt \rfloor} p_i + (nt - \lfloor nt \rfloor)p_{\lfloor nt \rfloor + 1}, \quad t \in [0, 1].$$

Proposition (Degenerate distribution)

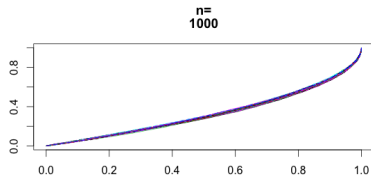
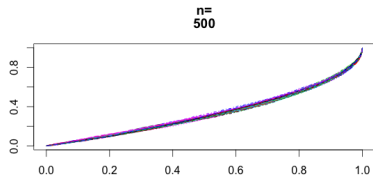
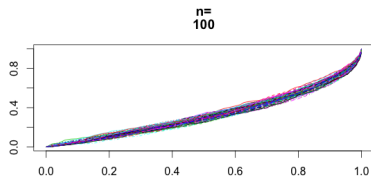
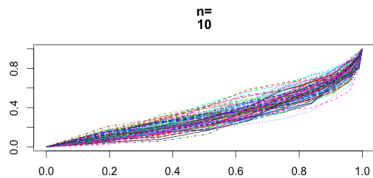
1. **Algorithm of Chen et al.**

Under a uniform partition, in $C([0, 1])$ with uniform topology: Y_n converges in probability to $\gamma(t) = t$; the process $\sqrt{n}(Y_n(t) - t)$ converges in distribution to a standard Brownian Bridge process.

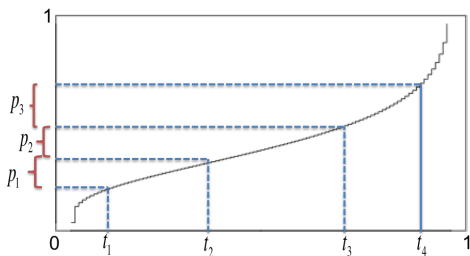
2. **Generalised version**

Under some conditions on F , Y_n converges in probability to $F^{-1}(t)$ in $C[0, 1]$ with uniform topology.

Example with F as Beta(1,2)



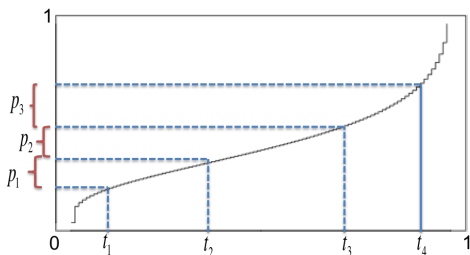
The algorithm can be salvaged ...



There are two main ingredients in the algorithm:

- ▶ Construction of partition $0 < t_1 < \dots < t_n < 1$ of $[0, 1]$;
- ▶ sampling of increments from a distribution on the unit simplex.

The algorithm can be salvaged ...



There are two main ingredients in the algorithm:

- ▶ Construction of partition $0 < t_1 < \dots < t_n < 1$ of $[0, 1]$;
- ▶ sampling of increments from a distribution on the unit simplex.

Choosing a **random** partition does the trick.

Modified algorithm with random partition

1. Choose $\theta > 0$;
2. discretize $[0, 1]$ with **order statistics**
 $0 =: t_0 < t_1 < t_2 < \dots < t_{n-1} < t_n := 1$ of a random sample from distribution function **H** on $[0, 1]$;

Modified algorithm with random partition

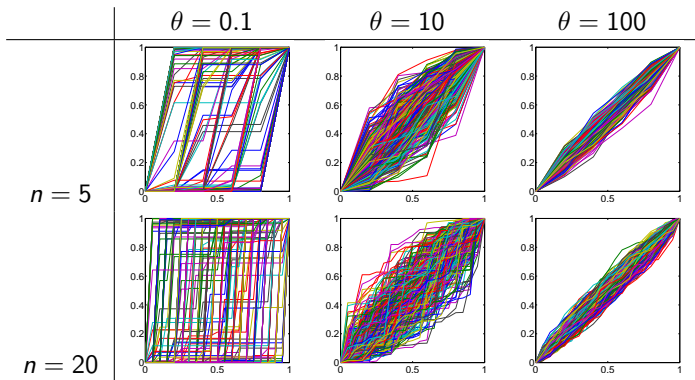
1. Choose $\theta > 0$;
2. discretize $[0, 1]$ with **order statistics**
 $0 =: t_0 < t_1 < t_2 < \dots < t_{n-1} < t_n := 1$ of a random sample from distribution function H on $[0, 1]$;
3. sample an **n -dimensional Dirichlet distributed random vector**
 (p_1, \dots, p_n) with parameters set to $\theta (t_{1:n} - t_{0:n}, \dots, t_{n:n} - t_{n-1:n})$;

Modified algorithm with random partition

1. Choose $\theta > 0$;
2. discretize $[0, 1]$ with **order statistics**
 $0 =: t_0 < t_1 < t_2 < \dots < t_{n-1} < t_n := 1$ of a random sample from distribution function **H** on $[0, 1]$;
3. sample an **n -dimensional Dirichlet distributed random vector**
 (p_1, \dots, p_n) with parameters set to $\theta (t_{1:n} - t_{0:n}, \dots, t_{n:n} - t_{n-1:n})$;
4. construct a warp map on $[0, 1]$ by linear interpolation.

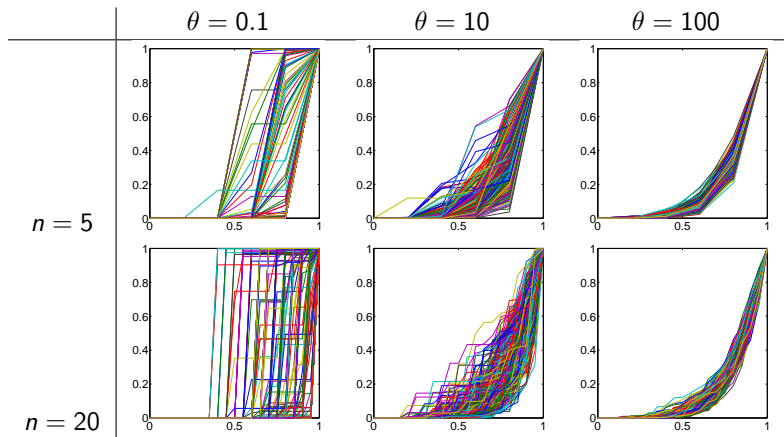
Example

Samples of warps with partition based on $H(t) = t$



Example

Samples of warps with partition based Beta (5,1) CDF as H



Justification for modified algorithm

- ▶ Consider partition based on H .
- ▶ Independently, let (p_1, \dots, p_n) obtained as spacings of an i.i.d sequence x_i from a density f (not necessarily Dirichlet distributed).

Justification for modified algorithm

- ▶ Consider partition based on H .
- ▶ Independently, let (p_1, \dots, p_n) obtained as spacings of an i.i.d sequence x_i from a density f (not necessarily Dirichlet distributed).
- ▶ Let $\lambda(x) = \theta \int_x^\infty \frac{e^{-y}}{y} dy$ for $\theta > 0$.
- ▶ Set $v_1 = p_1$ and $v_i = p_1 + \dots + p_i$, $i = 2, \dots, n$ and consider the transformed random variables $z_{i,n} = \lambda^{-1}(nf(F^{-1}(\zeta_{i,n})))v_i$ where $0 \leq \zeta_{i,n} \leq 1$ is a deterministic sequence such that $\max_{1 \leq i \leq n} |\frac{i}{n} - \zeta_{i,n}| = O(1/n)$.

Process based on random partition

Theorem

- ▶ Under some conditions on f , the *linearly interpolated* version of the process

$$G_n(t) := \sum_i \lambda^{-1}(z_{i,n}) \mathbb{I}_{t_i \leq t}, \quad t \in [0, 1],$$

converges weakly to the time-changed *pure jump Gamma process* $\mathcal{G} \circ H$ in the Skorohod M_1 topology (J_1 topology is too strong).

Process based on random partition

Theorem

- ▶ Under some conditions on f , the *linearly interpolated* version of the process

$$G_n(t) := \sum_i \lambda^{-1}(z_{i,n}) \mathbb{I}_{t_i \leq t}, \quad t \in [0, 1],$$

converges weakly to the time-changed *pure jump Gamma process* $\mathcal{G} \circ H$ in the Skorohod M_1 topology (J_1 topology is too strong).

- ▶ $\mathcal{D}^\theta \circ H = \mathcal{G}(H(t))/\mathcal{G}(H(\theta))$ is referred to as the *Dirichlet process* with sample paths as warp maps of $[0, 1]$ with

$$\mathbb{E} \mathcal{D}^\theta \circ H = H, \quad \forall \theta.$$

Interpretation of $\mathbb{P}_{H,\theta}$, the law of $\mathcal{D}^\theta \circ H$

Conditioned on a partition $0 =: t_{0:n} < t_{1:n} < \dots < t_{n-1:n} < t_{n:n} := 1$ from H ,

$$\begin{aligned} & \mathbb{P}_{H,\theta}(\gamma(t_{1:n}) \in dx_1, \dots, \gamma(t_{n-1:n}) \in dx_{n-1}) \\ &= \frac{\Gamma(\theta)}{\prod_{i=1}^n \Gamma(\theta(t_{i:n} - t_{i-1:n}))} \prod_{i=1}^n (x_i - x_{i-1})^{(\theta(t_{i:n} - t_{i-1:n}))} dx_1 \dots dx_{n-1}. \end{aligned}$$

Interpretation of $\mathbb{P}_{H,\theta}$, the law of $\mathcal{D}^\theta \circ H$

Conditioned on a partition $0 =: t_{0:n} < t_{1:n} < \dots < t_{n-1:n} < t_{n:n} := 1$ from H ,

$$\begin{aligned} & \mathbb{P}_{H,\theta}(\gamma(t_{1:n}) \in dx_1, \dots, \gamma(t_{n-1:n}) \in dx_{n-1}) \\ &= \frac{\Gamma(\theta)}{\prod_{i=1}^n \Gamma(\theta(t_{i:n} - t_{i-1:n}))} \prod_{i=1}^n (x_i - x_{i-1})^{(\theta(t_{i:n} - t_{i-1:n}))} dx_1 \dots dx_{n-1}. \end{aligned}$$

- ▶ $\mathbb{P}_{H,\theta}$ is push-forward of the well-known Dirichlet process⁴ on $\mathcal{P}[0, 1]$, the set of prob measures on $[0, 1]$, under the map that takes a probability measure to its quantile function.

⁴ T. Ferguson (1973). *Annals of Statistics*. 209–230

Comments

- ▶ $\mathbb{P}_{H,\theta}$ can be centred at desired warp map: choice of H when constructing the random partition.
- ▶ θ acts like a variance parameter.

Some properties of $\mathbb{P}_{H,\theta}$

- ▶ It has **full support** on set of warp maps Γ for every θ (several topologies coincide).

Some properties of $\mathbb{P}_{H,\theta}$

- ▶ It has **full support** on set of warp maps Γ for every θ (several topologies coincide).
- ▶ For every $\gamma \in \Gamma$, $\gamma_{\#}\mathbb{P}_{H,\theta}$ is absolutely continuous w.r.t $\mathbb{P}_{H,\theta}$ (quasi-invariance under composition).

Some properties of $\mathbb{P}_{H,\theta}$

- ▶ It has **full support** on set of warp maps Γ for every θ (several topologies coincide).
- ▶ For every $\gamma \in \Gamma$, $\gamma_{\#}\mathbb{P}_{H,\theta}$ is absolutely continuous w.r.t $\mathbb{P}_{H,\theta}$ (quasi-invariance under composition).
- ▶ When restricted to $[a, b]$ and rescaled, the resulting distribution is $\mathbb{D}_{\theta(H(b)-H(a))}$ (**Self-similarity**).
- ▶ Independent of $\mathbb{D}_{H,\theta}$ on $[0, 1] \setminus [a, b]$ except at a and b (**'Markov'**).

Some properties of $\mathbb{P}_{H,\theta}$

- ▶ It has **full support** on set of warp maps Γ for every θ (several topologies coincide).
- ▶ For every $\gamma \in \Gamma$, $\gamma_{\#}\mathbb{P}_{H,\theta}$ is absolutely continuous w.r.t $\mathbb{P}_{H,\theta}$ (quasi-invariance under composition).
- ▶ When restricted to $[a, b]$ and rescaled, the resulting distribution is $\mathbb{D}_{\theta(H(b)-H(a))}$ (**Self-similarity**).
- ▶ Independent of $\mathbb{D}_{H,\theta}$ on $[0, 1] \setminus [a, b]$ except at a and b (**'Markov'**).
- ▶ As $\theta \rightarrow 0$, $\mathbb{D}_{H,\theta}$ converges to uniform distribution on the set $\{\mathbb{I}_{[H(t), 1]} : 0 \leq t \leq 1\}$;
- ▶ as $\theta \rightarrow \infty$, $\mathbb{D}_{H,\theta}$ converges to point mass at $H(t)$.

$\mathbb{P}_{H,\theta}$ generates warps with jumps. . .

Jumps correspond to large deformations of subsets of $[0, 1]$. How large?
How often do they occur?

$\mathbb{P}_{H,\theta}$ generates warps with jumps. . .

Jumps correspond to large deformations of subsets of $[0, 1]$. How large? How often do they occur? Let $\xi_{i,n} := np_i - \log n$ be normalised increments.

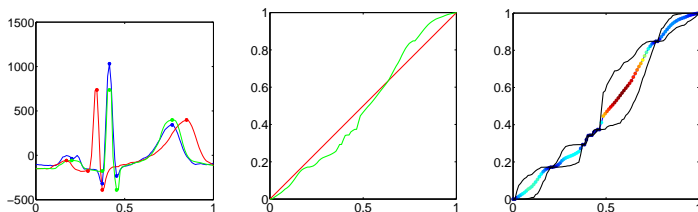
Consider the process $Y_n(t) := \sum_{i=1}^{\lfloor nt \rfloor} [\xi_i - E(\xi_i \mathbb{I}_{\xi_i \leq 1})]$, $0 \leq t \leq 1$.

Theorem

The sequence Y_n converges weakly in the J_1 topology to a real-valued Levy jump process with Levy measure $\nu(dy) = e^{-y} dy$ in $D[0, 1]$.

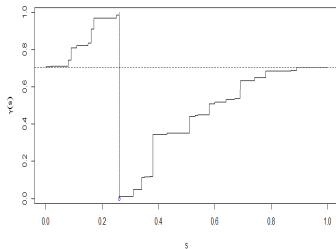
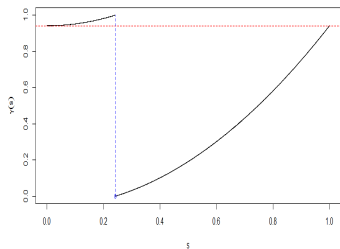
ECG Data: Bayesian model on Ambient/Top space

- ▶ Gaussian likelihood on $q_1 - q_2(\gamma)|\gamma$, where $q_i, i = 1, 2$ are Square Root Velocity transform (SRV) of $f_i, i = 1, 2$.
- ▶ $\mathbb{D}_{H,\theta}$ prior on Γ with $H(t) = t$.



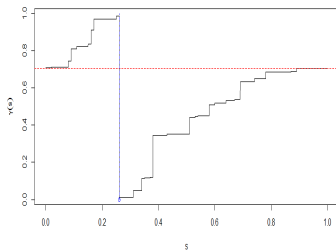
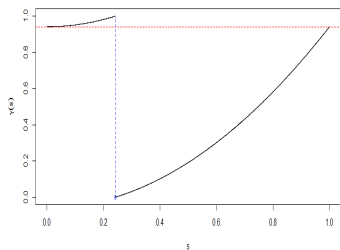
Green: Aligned function; estimated warp map. (Pointwise) Posterior credible intervals. (**Blue:** less uncertainty; **Red:** more uncertainty).

Sampling when $D = \mathbb{S}^1$ by unwrapping



$$\left\{ \text{AC warp maps of } \mathbb{S}^1 \right\} \xrightarrow{\text{Bijection}} \left\{ \text{AC warp maps of } [0, 1] \right\} \times \mathbb{S}^1$$

Sampling when $D = \mathbb{S}^1$ by unwrapping

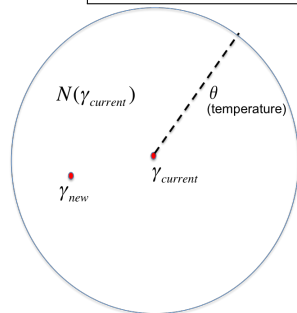


$$\left\{ \text{AC warp maps of } \mathbb{S}^1 \right\} \xrightarrow{\text{Bijection}} \left\{ \text{AC warp maps of } [0, 1] \right\} \times \mathbb{S}^1$$

1. Choose c from μ on $[0, 1]$ (by identifying \mathbb{S}^1 with \mathbb{R}/\mathbb{Z});
2. Sample γ from $\mathbb{D}_\theta \circ H$; and
3. Set $\gamma_s(t) := (\gamma(t) + c) \bmod 1$.

Simulated Annealing with $\mathbb{P}_{H,\theta}$

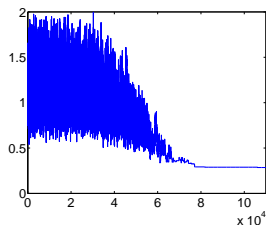
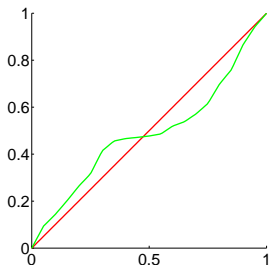
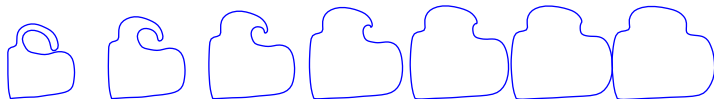
Solve: $\arg \min_{\gamma \in \Gamma} d(f_1(t), f_2(\gamma(t)))$



- ▶ Choose $\gamma_{new} \in N(\gamma_{current})$ by sampling $\mathbb{P}_{\gamma_{current}, \theta}$ centered at $\gamma_{current}$;
- ▶ compute $\Delta = d(f_1(t), f_2(\gamma_{new}(t)))$;
- ▶ if $\Delta \leq 0$, $\gamma_{current} \leftarrow \gamma_{new}$, else $\gamma_{current} \leftarrow \gamma_{new}$ with prob $e^{-\frac{\Delta}{\theta}}$;
- ▶ repeat.

Aligning shapes of closed curves in \mathbb{R}^2 : Simulated annealing

Geodesic path between leftmost and rightmost figures under SRVF.



Summary

- ▶ Landmark constraints under curves impose constraints on warp maps.
- ▶ For alignment with landmarks $\mathbb{P}_{H,\theta}$ is compatible with **Focus invariance** and **Decomposability**.
- ▶ These characterize $\mathbb{P}_{H,\theta}$.
- ▶ Algorithm is trivial to implement, and can generate maps from distribution centered at derived at any warp map.

Details and more examples in paper:
Partition-based sampling of warp maps for curve alignment.
arXiv:1708.04891.